Neural Network Quantum State Tomography

Mo Abedi Supervised by Chae-Yeun Park

Department of Physics

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Outline

- **1. Mathematical Preliminaries**
- 2. RBM Quantum State Tomography
- 3. RNN Quantum State Tomography
- 4. Summary



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• Basic idea: can we reconstructing quantum states from measurements? How to do so?



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Definition

An informationally complete positive-operator valued measure [1] (POVM), Π_i is the set of operators on \mathcal{H} such that:

 $\Pi_{i} \geq 0 \text{ Semi-Positivity}$ $\sum_{i} \Pi_{i} = 1$ $p_{i} = \text{Tr} (\rho \Pi_{i}) \text{ Born rule}$ $\{\Pi_{i}\} = \text{span}(\mathcal{B}(\mathcal{H})) \text{ Informational Completeness}$

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Preposition

The density operator can be written as:

$$\rho = \sum_{ij} p_i T_{ij}^{-1} \Pi_j$$

Where:

$$T_{ij} = \operatorname{Tr}\left(\Pi_i \Pi_j\right)$$

Is the called the overlap matrix.



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Note that the overlap matrix may not be invertable



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Example

A set of POVMs are given by Pauli-4 Tetrahedral operators:

$$\Pi_{Tetra} = \left\{ \Pi_{i} = \frac{1}{4} \left(1 + s_{i} \cdot \sigma \right) \right\}$$

$$s_{0} = (0, 0, 1) \quad s_{1} = \left(\frac{2\sqrt{2}}{3}, 0, -\frac{1}{3} \right)$$

$$s_{2} = \left(-\frac{2\sqrt{2}}{2}, \sqrt{\frac{2}{3}}, \frac{1}{3} \right) \quad s_{3} = \left(-\frac{2\sqrt{2}}{3}, -\sqrt{\frac{2}{3}}, -\frac{1}{3} \right)$$

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Example

A set of POVMs are given by Pauli-4 Tetrahedral operators:

$$\Pi_{0} = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \quad \Pi_{2} = \frac{1}{12} \begin{pmatrix} 2 & -\sqrt{2} - \sqrt{6}i \\ -\sqrt{2} + \sqrt{6}i & 4 \end{pmatrix}$$

$$\Pi_{1} = \frac{1}{6} \begin{pmatrix} 1 & \sqrt{2} \\ \sqrt{2} & 2 \end{pmatrix} \quad \Pi_{3} = \frac{1}{4} \begin{pmatrix} 2 & -\sqrt{2} + \sqrt{6}i \\ -\sqrt{2} - \sqrt{6}i & 4 \end{pmatrix}$$

$$T^{-1} = \begin{pmatrix} 5 & -1 & -1 & -1 \\ -1 & 5 & -1 & -1 \\ -1 & -1 & 5 & -1 \\ -1 & -1 & -1 & 5 \end{pmatrix}$$

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Definition

The likelihood is a measure of the degree of belief in the hypothesis that for a particular data set D, the system was prepared in the quantum state ρ [2]. For QST, we have the multinomial distribution:

$$\mathcal{L}\left(\mathcal{D}|\rho\right) = \mathcal{N}\prod_{i}^{k} p_{i}^{f_{i}} = \frac{n!}{\prod_{i}^{k} f_{i}!} \prod_{i}^{k} \operatorname{Tr}\left(\rho \Pi_{i}\right)^{f_{i}}$$

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 Consider the negative log instead which we call the cost function

$$\mathcal{C} = -\sum_{i} f_{i} \ln p_{i} = -\sum_{i} f_{i} \ln [\operatorname{Tr} (\rho \Pi_{i})] = \mathcal{D}_{\mathcal{KL}} (\mathcal{D}|\rho) + \mathbb{H}_{\mathcal{D}}$$

Where D_{KL} is the KL divergence, a measure of how close the actual probability distribution is to our measured data. We want to minimise this.



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Preposition

The variation of C w.r.t. ρ is given by:

$$\delta C(\rho) = C(\rho - \delta \rho) - C(\rho) = \operatorname{Tr} \left((R - 1)\rho(R - 1) \right)$$
$$\delta \rho = (R - 1) \rho + \rho \left(R - 1 \right)$$

And is 0 when:

$$R\rho = \rho R = \rho$$

Where:

$$R = -\sum_{i} \frac{t_i}{p_i} \Pi_i$$

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Algorithm (*R* ρ *R*)

- Start with maximally mixed state ρ = 1/dim(H) 1 and some precision ε and set the trace distance TD > ε
- While $TD > \epsilon$:

Calculate $R_{(k)}$ Compute trace distance $\frac{1}{2}$ Tr $(|R_{(k)}\rho_{(k)} - \rho_{(k)}|) = TD$ Compute $\delta\rho_{(k)} = ((R_{(k)} - 1))\rho_{(k)} + \rho_{(k)}(R_{(k)} - 1))$ Update $\rho_{(k+1)} = \rho_{(k)} + \alpha\delta\rho_{(k)}$

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Measures of Fidelity, Trace Distance, and Relative Entropy with respect to Epochs



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 $\begin{pmatrix} 0 \\ 3 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

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- The activation probabilities are calculated as follows:

$$p\left(\mathbf{v}_{i}^{k}|h,\lambda\right) = \frac{\exp\left(b_{i}^{k}+\sum_{j}h_{j}W_{ij}^{k}\right)}{\sum_{l}\exp\left(b_{i}^{l}+\sum_{j}h_{j}W_{ij}^{l}\right)} = \operatorname{sm}\left(b_{i}^{k}+\sum_{j}h_{j}W_{ij}^{k}\right)$$
$$p\left(h_{j}|\mathbf{v},\lambda\right) = \sigma\left(c_{j}+\sum_{i}\sum_{k}v_{i}^{k}W_{ij}^{k}\right)$$

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$$p\left(v_{i}^{k}|h,\lambda\right) = \frac{\exp\left(b_{i}^{k} + \sum_{j} h_{j} W_{ij}^{k}\right)}{\sum_{l} \exp\left(b_{i}^{l} + \sum_{j} h_{j} W_{ij}^{l}\right)} = \operatorname{sm}\left(b_{i}^{k} + \sum_{j} h_{j} W_{ij}^{k}\right)$$
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 After calculating probabilities, we sample using Binomial/Bernoulli or Multinomial/Categorical distributions



Algorithm (*CD_k* algorithm for Quantum State Tomography)

- For epoch in total epochs:
- For mini-batch in training data:
- From input data v, sample h after calculating p(h|v)
- For k steps:
- Sample v' after calculating p(v'|h') (h for k = 1)
- Sample h' after calculating p(h'|v')
- Calculate $\left\langle \frac{\partial E(v,h)}{\partial \lambda} \right\rangle \left\langle \frac{\partial E(v',h')}{\partial \lambda} \right\rangle$
- Update parameters λ



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Measures of Fidelity, Trace Distance, and Relative Entropy with respect to Epochs



Dont always need the density matrix. Can estimate expectations values directly:

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$$\begin{split} \langle \mathcal{O} \rangle &= \sum_{i} \mathcal{Q}_{i}^{\mathcal{O}} \boldsymbol{p}_{i} \\ \mathcal{Q}_{i}^{\mathcal{O}} &= \sum_{i} \operatorname{Tr} \left(\mathcal{O} \Pi_{j} \right) T_{ji}^{-1} \end{split}$$

Have to take into account local depolarising noise.



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Dont always need the density matrix. Can estimate expectations values directly:

- Have to take into account local depolarising noise.
- In general, RBMs take long time to train for small noise [3].



Sequential feed forward networks with notion of "memory"
 [5]. Used often in word prediction and machine translation
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• Mathematically:





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$$\begin{aligned} \mathbf{H}_{t} &= \mathcal{F}_{1} \left(\mathbf{X}_{t} W_{xh} + \mathbf{H}_{t-1} W_{hh} + b_{h} \right) \\ \mathbf{O}_{t} &= \mathcal{F}_{2} \left(\mathbf{H}_{t} W_{ho} + b_{o} \right) \end{aligned}$$

• Simple RNNs fail to capture long-term dependencies and cause vanishing or exploding gradients [5].

$$C = \sum_{t=1}^{l} C_t$$
$$\frac{\partial C}{\partial W_{hh}} \sim \sum_{k}^{t} \frac{\partial \mathbf{H}_t}{\partial \mathbf{H}_k} \frac{\partial \mathbf{H}_k}{\partial W_{hh}}$$
$$\sim \sum_{k}^{t} (W_{hh}^T)^{t-k} \mathbf{H}_k$$

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 Have to introduce better long term dependencies.
 Examples are LSTM and GRU. LSTM have the following structure [5]:



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- The final layer represents the cumulative output of the cell (multiplied with the cell "memory")
- Solves the vanishing gradient as you have extra terms:

$$\frac{\partial \mathcal{C}}{\partial W_{hh}} \sim \frac{\partial \mathbf{C}_t}{\partial \mathbf{C}_k}$$



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- Can then recover the full distribution:

$$p(m_1...m_n) = p(m_1)p(m_2|m_1)...p(m_n|m_1...m_{n-1})$$

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• RNN train faster than RBMs [3]. The required training data for an RNN linearly with *N*, which is remarkable.

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- Traditional methods like MLE are too slow for large number of qubits
- Generative modelling from provide ways to earn probability distributions of measurements and are a excellent choice for the problem at hand
- RBMs and RNNs can be used for QST, the latter scales linearly with number of qubits

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The End

All questions welcome!

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